

Behavioral Modeling in HOLOBALANCE





Problem Definition

OUTPUT SPECIFICATION

The dynamics of one individual's behavior during an exercise session are captured by the level of frustration experienced by the user at each exercise.

NASA TLX Task Load Index NASA Task Load Index

Frustration: "How insecure, discouraged, irritated, stressed, and annoyed were you?"

INPUT SPECIFICATION

Re-instructions Adherence to Instructions Performance **Exercise Type**

Disease Status Symptoms Baseline Experience with Technology Health/Disease Belief/Perception

Problem Formulation

EXERCISE SESSION

The state of the system at time t is represented by a set of random variables:

$$Z^{(t)} = \{U^{(t)}, X^{(t)}, Y^{(t)}\}, t = 0, ..., T$$

 $U^{(t)}$, $X^{(t)}$, $Y^{(t)}$: Input, hidden and output variables of the model

ASSUMPTIONS

Markov Assumption $Z^{(t+1)} \perp Z^{(0:t-1)} \mid Z^{(t)}$

$$P(Z^{(0)}, Z^{(1)}, ..., Z^{(T)})$$

$$= P(Z^{(0)}) \cdot P(Z^{(1)} | Z^{(0)}) \cdot ... \cdot P(Z^{(T)} | Z^{(T-1)})$$

Time Invariance $P(Z^{(t)}|Z^{(t-1)})=P(Z'|Z) \ \forall t>0$

DYNAMIC BAYESIAN NETWORK

Initial state distribution $P(Z^{(0)})$

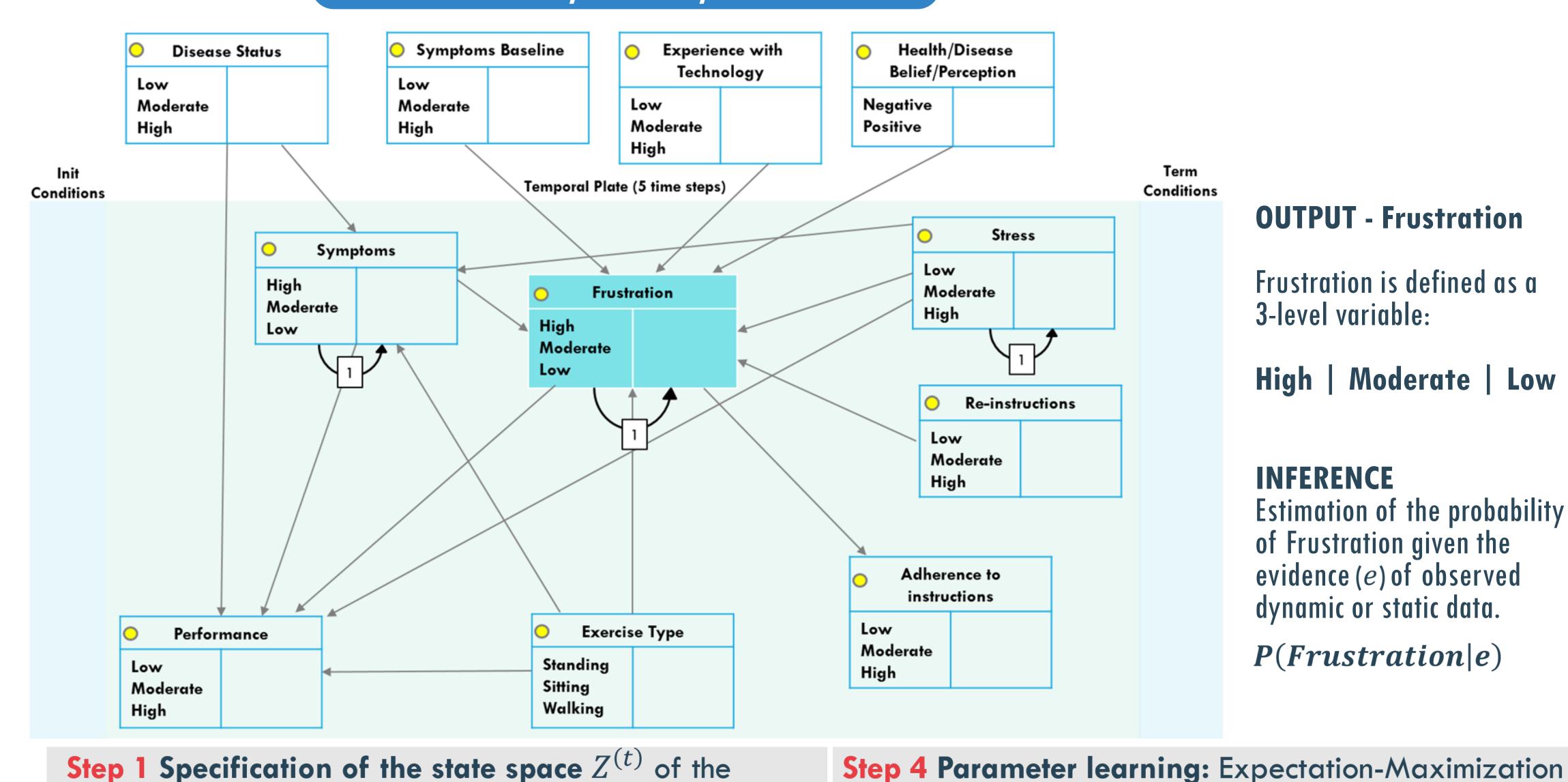
Transition model

$$P(Z^{(t)}|Z^{(t-1)}) = \prod_{i=1}^{n} P(Z_i^{(t)}|Par(Z_i^{(t)}))$$

Testing the inference performance of the initial DBN model Mo

Methodology

HOLOBALANCE Dynamic Bayesian Network



OUTPUT - Frustration

Frustration is defined as a 3-level variable:

Moderate Low

INFERENCE

Estimation of the probability of Frustration given the evidence (e) of observed dynamic or static data.

P(Frustration|e)

module

Video capturing

after exercise performed



Symptoms Baseline: Low | Health/Disease Belief/Perception: Positive

Subjects:

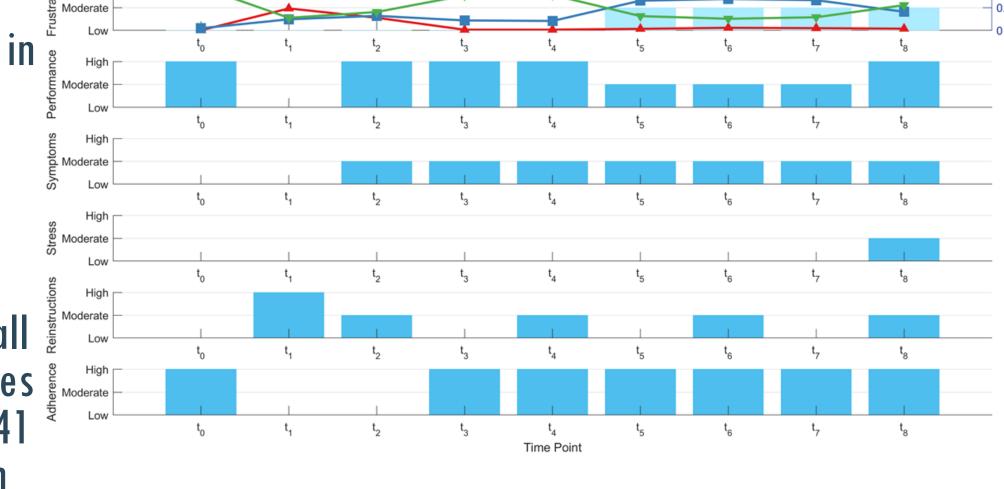
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Data from 5 subjects in § Athens

Results

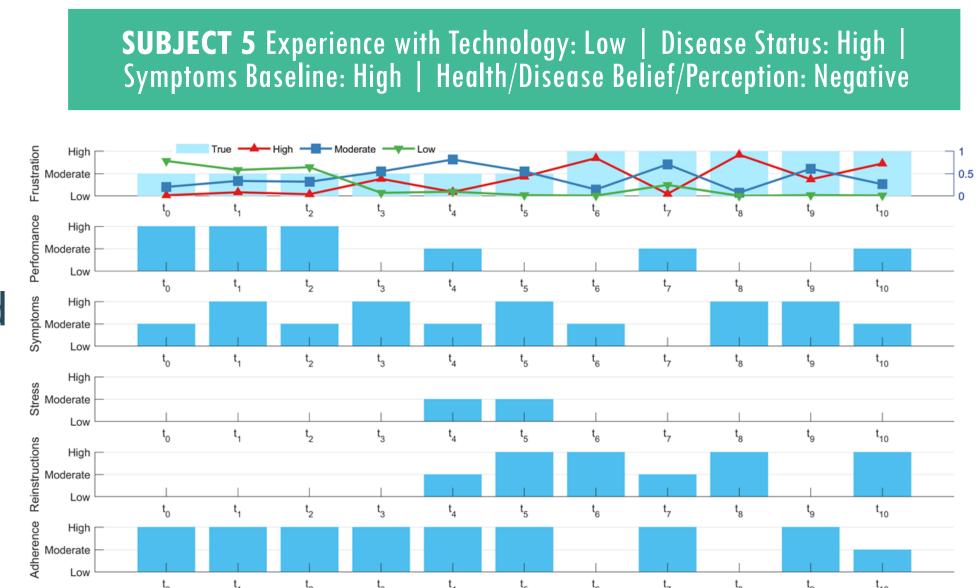
Procedure:

Each patient performed up to 36 exercises which are all the flowchart exercises & Moderate with progressions (141 executed exercises in total)



Patients used Holobalance sensing

Frustration was asked



system

Step 3 Initialization of the state distribution $P(Z^{(0)})$ and the conditional probability $P(\mathbf{Z}^{(t)}|\mathbf{Z}^{(t-1)})$ ($\mathbf{M_0}$)

Step 2 Specification of the structure of the DBN

References

https://humansystems.arc.nasa.gov/groups/TLX

validation

• K. Murphy, Machine Learning: A Probabilistic Perspective, The MIT

(EM) learning (Model M_{EM})

Step 5 Inference – The Clustering algorithm

Step 6 Evaluation — Evaluation of the classification

performance of M_{EM} based on 10-fold cross-

- Lin & Druzdzel, Uncertainty in Artificial Intelligence Conf.,1997
- Yuan & Druzdzel, Uncertainty in Artificial Intelligence Conf., 2003 GeNIe Modeler, SMILE Engine, BayesFusion, LLC, http://www.bayesfusion.com/

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